**Abstract**

- Nematode Caenorhabditis (C.) elegans is a roundworm which is one of the researcher’s choice for neuronal development studies and molecular and developmental biology studies.
- Locomotory behavior of C.Elegans is studied by recording the worm movement and then the recorded video data is processed to determine the path, speed, and trajectory of the worm, in order to identify higher level functions and behaviors.
- This work aimed to accelerate the processing of the C.Elegans tracking data through inter-node parallelism.
- Achieved two to three orders of magnitude performance improvement when comparing to the original Java-based processing system.

**Motivation**

- The C.Elegans is widely used for unraveling the principles underlying functional neural circuits.
- C.Elegans was the first multicellular organism to have its whole genome sequenced.
- The worms have a simple neural network with exactly 302 neurons and approximately 7000 synaptic connections.
- The worm moves in a sinusoidal fashion and the locomotion relies on muscular contraction and neuromuscular transmissions.
- The goal was to understand and study the locomotory behavior of the worm at various environments like a food deprived situation for example, for a long duration of time. The locomotory behavior has also been been studied under various conditions like different mutations to the genetic structure of the worm. Knowledge gained from these studies could be applied to complex nervous systems like those of mammals.

**Experimental Setup**

A setup consisting of both hardware and software was designed to study C.Elegans locomotory behavior. The setup was designed specifically to track one worm at a time.

- Hardware consisted of a base to hold the agar plate with the worm, a three axis movable camera mechanism and a small computer to control the camera.
- Tracking software is responsible for capturing the raw video (webcam capture API Sanos) of the worm movement in the agar plate.
- The software triggers camera movement to keep track and follow the worm in the agar plate.

**Analysis Design and Implementation**

- Initial implementation in Java
- Ported Java code to different implementations in C and C++
- C++ with OpenCV
- C with PThreads
- C with MPI
- C with Swift/T

**Performance Evaluations**

- Compared and Evaluated all implementation
- S/T-48: Swift/T implementation running on 48 threads. MPI-48: MPI implementation running on a single system with 48 threads
- C-48: C implementation with 48 threads
- Dataset consisted of 47000 images extracted at various resolutions
- Testbed : Chameleon cloud with 24-core Intel Haswell processors and 128GB RAM

**Conclusion**

- Java implementation has significant overhead compared to C/C++
- At higher resolutions, performance degradation in Java is even more pronounced (speedups of 2 to 3 orders of magnitude are common)
- Low resolution dataset computation cost reduced from 53 seconds to 2.2 seconds
- High resolution dataset computation cost reduced from over 10 hours down to under 30 seconds
- Swift/T and MPI performance are comparable to C with Pthreads; we will explore Swift/T and MPI in multi-node environments in future work as there are no code changes needed

**References**


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**Accelerating Worm Segmentation through inter-node parallelism**

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**Analysis Design and Implementation**

- Box Blur algorithm.
- Convert the video to individual frames(images)
- Convert the image to grayscale
- Blur(smoothen) Image. Use Box Blur algorithm.
- Find the largest Connected component in the binary image to detect the worm body and position
- Thresholding Technique to convert the pixels to binary
- Plot coordinates and calculate the worm body area

To track the worm location during its movement, centroid or center of mass of worm in each frame is calculated. Centroid is calculated as the average of x and y coordinate of all M pixels on the worm body:

\[
(C_x, C_y) = \left( \frac{\sum_{i=1}^{M} x_i}{M}, \frac{\sum_{i=1}^{M} y_i}{M} \right)
\]